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Investigation of the influence of nonoccurrence sampling on Landslide Susceptibility Assessment using Artificial Neural Networks

Luísa Vieira Lucchese^{1,3}, Guilherme Garcia de Oliveira², Olavo Correa Pedrollo¹

Abstract

Landslide susceptibility assessment using Artificial Neural Networks (ANNs) requires occurrence (landslide) and nonoccurrence (not prone to landslide) samples for ANN training. We present empirical evidence that a priori intervention on the nonoccurrence samples can produce models that are improper for generalization. Thirteen nonoccurrence cases based on GIS data from Rolante River basin (828.26 km²) in Brazil are studied, divided in three groups. The first group was based on six combinations of buffers with different minimum and maximum distances from the mapped scars (BO). The second group (RO) acquired nonoccurrence only from a rectangle in the lowlands, known for not being susceptible to landslides. For BR, six alternatives respectively to BO were presented, with the inclusion of nonoccurrence samples acquired from the same rectangle used for RO. Accuracy (acc) and the Area Under Receiving Operating Characteristic Curve (AUC) were calculated. RO resulted in perfect discrimination between susceptible and not susceptible to landslides (acc=1 e AUC=1). This occurred

 $^{^1}$ Instituto de Pesquisas Hidráulicas, Universidade Federal do Rio Grande do Sul, Av. Bento Gonçalves 9500, 91501-970, Porto Alegre, RS, Brazil

²Departamento Interdisciplinar. Universidade Federal do Rio Grande do Sul. Rodovia RS 030, 11700, km 92. Emboaba, Tramandaí/RS, Brazil. CEP 95590-000.

³Corresponding author.

E-mail address: luisa.lucchese@ufrgs.br (Luísa Lucchese) Declarations of interest: none.

because the model simply provided susceptible classification to points in which attributes are different from those in the rectangle, harming the classification of nonoccurrence sampling points outside the rectangle. RO map shows large areas classified as susceptible which are known to be non-susceptible. In BR, sampling points from the rectangle, which are easy to classify, were added to the verification sample of BR. Average acc for BO 00m (minimum buffer distance to scars of 0 m): 89.45%, average acc for BR 00m: 92.33%, average AUC for BO 00m: 0.9409, average AUC for BR 00m: 0.9616. Maps of groups BO and BR were alike. This indicates that metrics can be artificially risen if biased samples are added, although the final map is not visibly affected. To avoid this effect, the employment of easily classifiable samples, generated based on expert knowledge, should be made carefully.

Keywords: landslides, mass movements, South America, Rio Grande do Sul Brazil, sediment transport, geomorphology

1 1. Introduction

Landslide susceptibility assessment is the process that establishes the likelihood of landslide occurrence in a given area, using suitable terrain factors (Sorriso Valvo, 2002). A possible way of assessing natural disasters hazard is to produce, using Geographic Information Systems (GIS) techniques, maps of susceptibility to the disaster. In order to generate these maps, data from previous landslides is usually necessary. This relates to one of the general principles of landslide hazard zonation, that is the past is the key to the future (Varnes, 1984; Fell et al., 2008).

Landslide susceptibility assessment can be performed by a range of methods, that are comprised of two main approaches: qualitative and quantitative. Qualitative approaches are usually based on on-site observations and combinations of index maps elaborated by experts. One example is Anbalagan (1992) which used the

Landslide Hazard Evaluation factor. Aleotti and Chowdhury (1999) discuss 14 that, decades ago, on-site survey was essentially the only option available that 15 was not prone to subjectivity involved, though it could be costly and dangerous. 16 On the other hand, quantitative approaches are based on statistical models 17 (Lee and Min, 2001; Regmi et al., 2014; Hussin et al., 2016) or geotechnics 18 approaches (Gökceoglu and Aksoy, 1996; Fall et al., 2006; Gutiérrez-Martín, 19 2020). Artificial Intelligence models may be considered included in the statistical 20 category, within the quantitative approach. 21

Artificial Intelligence (AI) is the theory and development of computer systems 22 with the ability to act resembling human intelligence. To date, several studies 23 have used AI methods for Landslide Susceptibility Mapping. AI methods used 24 in this knowledge area include but are not limited to Artificial Neural Networks 25 (ANNs) - used in the present paper as well as in the papers of Lee et al. 26 (2004) and Ermini et al. (2005), but also Random Forest (RF) - used by Catani 27 et al. (2013), Pourghasemi and Kerle (2016) and Dou et al. (2019) -, Rotation 28 Forest (RoF) - used by Chen et al. (2017b) -, Fuzzy Inference Systems (FIS) 29 employed by Ercanoglu and Gokceoglu (2002) and Kanungo et al. (2006) -, 30 Logistic Regression (LR) - employed by Ayalew and Yamagishi (2005) and Lee 31 (2005) -, and Naïve Bayes (NB) - used by Bui et al. (2012). 32

Some authors performed comparisons between AI methods. Most of the 33 papers that compared ANN to other methods for landslide susceptibility assessment 34 demonstrated that ANN models perform better than their counterparts. Yesilnacar 35 and Topal (2005) compared ANNs to LR and calculated the global accuracy 36 for both, which was 82.1% for ANN and 79.6% for LR. A comparison between 37 Dempster-Shafer, LR and ANN was made by Chen et al. (2017c). The accuracies 38 calculated for the validation set for the three methods were, respectively, 61.39%, 39 68.94% and 69.92%. Dou et al. (2018) used both ANN and LR, and concluded 40

ANN provided a higher accuracy. These findings are also supported by Gong et al. (2018), that also compared ANN and LR, obtaining 82.6% and 75.4% accuracies for ANN and LR, respectively. Braun et al. (2019) compared the accuracy of three methods, namely, Decision Trees, Bayesian Networks and ANNs, and ANNs were better at classifying the landslide areas, with some level of false alarm on the classification maps. Overall, many researchers found that ANNs tend to provide good accuracy for landslide prediction.

A large and growing body of literature has investigated the use of ANNs 48 for landslide susceptibility assessment. As ANNs are universal approximators 49 (Hornik et al., 1989), using the right training dataset, number of hidden neurons 50 and activation function for these neurons, one can possibly approximate any 51 existing function. However, it was not until the 2000s that studies on using 52 ANNs for landslide susceptibility assessment were first published. Some pioneer 53 papers on this subject were Lee et al. (2004), which used seven attributes to train 54 the ANN, Ermini et al. (2005), which used a Probabilistic Neural Network, and 55 Gomez and Kavzoglu (2005), which employed nine different terrain attributes 56 for training. More recently, many studies have been conducted in this area, such 57 as the works of Dou et al. (2015), which selected six out of 14 original attributes 58 for ANN training and employed them for landslide susceptibility assessment on 59 Osado Island, Japan, Chen et al. (2017a), that compared three different types 60 of models, including ANNs, and Braun et al. (2019), which used ANN models 61 for the same objective in Honduras. 62

Sampling locations and techniques used to train, validate and verify the ANNs and maps generated are, at some extent, unexplored in the methodology presentation of published papers in landslide susceptibility assessment. As Zhu et al. (2018) emphasize, the employment of nonoccurrence samples is very important to constrain the over-prediction of high susceptibility. Some papers do

not provide any information about nonoccurrence sites. Ortiz and Martínez-Graña 68 (2018) used half of landslide sites for training, but presented no information 69 about nonoccurrence samples used. Xiong et al. (2019) present some information 70 about the attributes in the occurrence samples, but nonoccurrence is not commented. 71 Bui et al. (2016) separates the landslide inventory in landslides used to train 72 and to verify the ANN model, but they do not provide the information about 73 nonoccurrence sites used to train. In the work of Can et al. (2019), it is stated 74 that equal numbers (196) of occurrence and nonoccurrence samples were used 75 to train the ANN, but neither the location nor the parameters of nonoccurrence 76 samples are presented. On the other hand, Zare et al. (2013) presented the 77 frequency ratio between occurrence and nonoccurrence for each factor used to 78 train the ANN, and Pham et al. (2017) showed the location of every point. 79

Still, to date there has been little agreement on the methods used to acquire 80 nonoccurrence (safe places, not prone to landslides) samples. Pradhan and Lee 81 (2010), Dou et al. (2018), Polykretis and Chalkias (2018) and Shirzadi et al. 82 (2019) used random points outside the landslide scars. Braun et al. (2019) 83 employed all locations with no landslides recorded as nonoccurrence samples, 84 and created copies of landslide-prone samples in order to have a balance of the 85 two classes on the training set. Merghadi et al. (2018) divided the randomly 86 sampled points in ten divisions, using nine of them to train and one to validate, 87 and repeated the sampling procedure five times. Their evaluation metrics were 88 averaged between the 50 models trained. Pham et al. (2017) presented the 89 location of all occurrence and nonoccurrence points used for training and for 90 validation on a map, on which it is possible to see the points are well-distributed. 91 Gomez and Kavzoglu (2005) selected nonoccurrence samples from places where 92 landslide initialization is not likely to happen, such as on river channels and 93 terrains with slope angles lower than five degrees. The accuracy achieved by 94

the ANN for areas mapped as not susceptible to landslides was about 95%. The generated map shows large areas as highly susceptible and appears to had been strongly influenced by Elevation attribute. Choi et al. (2010) executed an ANN trained for one location in another location. Analogously, in their study, nonoccurrence samples were taken from points in which the slope was zero. When the ANN models are applied to the areas for which they were calculated, large areas appear to have susceptibility indexes over 0.8.

Xiao et al. (2010) did not use ANNs but a Generalized Additive Model, 102 which is a variation of LR, to propose a method for artificially generating 103 nonoccurrence samples. This method is based on occurrence samples and is 104 called Target Space Exteriorization Sampling. Samples are created by changing 105 the values of one or more attributes so that they are out of the range considered 106 for susceptibility. They compared their method to other two approaches. One 107 of them is using random samples with a minimum distance of 85 m from the 108 scars (called Buffer Controlling Sampling). The other one is using these random 109 samples with outliers filtered out (called Iteratively Refined Sampling). They 110 concluded that the proposed sampling method provided satisfactory evaluation 111 metrics and a more desirable probability distribution of outputs than the other 112 two. Filtering outliers out generated higher metrics than using the original 113 (random) dataset. Analyzing this finding from a different point of view, higher 114 evaluation metrics could possibly be caused by this intervention, which eliminates 115 some of the nonoccurrence samples that would be hardest to classify. 116

In the paper of Hong et al. (2019), that compared four methods for nonoccurrence sampling using RF, the geographical locations from which the nonoccurrence samples could be acquired by each sampling method are shown. Also, it is possible to see that methods which exclude wider areas around the landslide scars result in susceptibility maps with large areas classified as susceptible, and this effect intensifies as the balance between occurrence and nonoccurrence
samples changes by the removal of some nonoccurrence samples. This was
observed by Hong et al. (2019) but the underlying causes were not researched.

Zhu et al. (2019) employed a similarity-based approach for acquiring nonoccurrence 125 samples for landslide susceptibility mapping using SVM, RF and LR. A reliability 126 index was calculated for nonoccurrence samples, based on how much those 127 samples attributes differ from the occurrence samples attributes. At some 128 extent, this can be considered expert knowledge intervention on the dataset. 129 Zhu et al. (2019) acknowledged that using samples with reliability index over 130 0.5 harms the correct classification of nonoccurrence areas, generating maps 131 that overestimate susceptible areas, even if the models based on these samples 132 showed the highest accuracy metrics. Their explanation is that, in these cases, 133 occurrence and nonoccurrence samples are too different. Nevertheless, the 134 possible non-applicability of metric comparisons for the analyzed cases was not 135 discussed. In theory, higher accuracies indicate better modeling capabilities, 136 however, Zhu et al. (2019) results can be seen in a new light. A possibility to be 137 contemplated is that nonoccurrence samples with higher reliability indexes can 138 be easier to classify by a data-driven model than samples with low reliability 139 indexes. However, this may bias the evaluation metrics calculated based on 140 them and possibly make them unsuited for direct comparisons. 141

About the occurrence sampling methods, a number of studies have begun to examine sampling strategies for landslide hazard assessment. Süzen and Doyuran (2004) proposed the seed cells method, in which the landslide occurrence samples would be acquired from zones that are considered to represent the undisturbed (i.e. before the occurrence of the event) morphological conditions, acquired from the vicinity of the landslide polygon. The location of these seed cells is acquired using a buffer from the mapped scars, upstream of the scars.

Wang et al. (2013) used logistic regression and employed a 50 m buffer of 149 the landslide seed cells. Only the location of occurrence samples is given by 150 the seed cell method, the location of nonoccurrence samples is not discussed. 151 Yilmaz (2010) investigated three possible techniques to select which area should 152 be included in the occurrence samples, using the location of landslide scars. 153 However, he did not elucidate how the nonoccurrence samples should be taken. 154 Yao et al. (2008), on the other hand, compared the use of two-class (occurrence 155 and nonoccurrence) Supporting Vector Machine (SVM) with one-class (occurrence 156 only) correspondent model, and detected that results improved when using the 157 two-class model, noticeably showing that nonoccurrence samples matter. 158

Evaluation metrics such as Area Under Receiver Operating Characteristic 159 (ROC) Curve (AUC) (DeLong et al., 1988) and accuracy (acc) are reported in 160 many papers of the research area. Although, in many of these papers, the base 161 samples (and their locations) used for calculating the evaluation metrics are not 162 presented. In some papers, only the test area was used for these calculations 163 (Kawabata and Bandibas, 2009: Merghadi et al., 2018), or a separate statistic 164 is calculated for the test set (Kumar et al., 2018). In others, the whole dataset 165 composed of training, validation - if present - and verification samples is used 166 to calculate the evaluation metrics (García-Rodríguez and Malpica, 2010; Zhu 167 et al., 2018). This is relevant because some groups of samples are remarkably 168 easier to classify than others. Does the criterion used to select nonoccurrence 169 samples for landslide susceptibility mapping influence the generalization ability 170 of the ANN model? Also, is it possible that, when we select easily classifiable 171 samples, we facilitate the modeling process, and attain inflated evaluation metrics. 172 without necessarily this correlating to a better generalization ability? 173

Notably, the results of the evaluation metrics will not be reliable if the experiment planning is not well conduced regarding the verification samples. One should notice that the best criteria are the evaluation metrics, but this is only true if the verification sample, used for comparison between models, is representative of the application areas studied, and subjected to same triggering factors. This paper discusses the necessity of classifications that are not obvious, to avoid biased resulting models. We therefore provide empirical evidence that the detection of bias on the resulting models is hard if the nonoccurrence verification samples are acquired from obvious nonoccurrence areas.

Overall, the studies here depicted highlight the need for more investigation 183 into the samples used to train, validate (when applicable) and verify the employed 184 ANNs. In this paper, we aim to show how different nonoccurrence sampling 185 techniques can influence the resulting susceptibility map and statistics. Notably, 186 nonoccurrence sampling based on expert knowledge of susceptibility, here represented 187 by acquiring nonoccurrence samples from the lowlands. If sampling is done 188 exclusively in the scars proximity, there is a risk that the model, because it 189 does not mark the lowlands as occurrence sites, fails when applied to a larger 190 area. This would make the specialist to limit the model application area to 191 places where, according to their expert knowledge, have greater probability to 192 be susceptible. In this case, they would determine (therefore, intervening) that 193 the other regions would be nonoccurrence sites. The inclusion of a rectangle in 194 the lowlands is based on making the model identify areas that are notably not 195 susceptible to landslides without the need to intervene during the application 196 of the model, intervening, although, in the sampling process. The idea is 197 interesting, but it should be analyzed so that we provide evidence on whether 198 it is successful. 199

Through a rather empirical approach, we aim to investigate how a sampling procedure in which the nonoccurrence points are acquired from areas known not to be prone to landslides influences the evaluation metrics. Thus, metrics can be affected in an apparently positive way, although inaccurate susceptibility maps can be generated. This sampling procedure, portrayed here, is based on the acquisition of samples from a lowland area on the valley, known not to be prone to landslides. In opposition, samples can be acquired from close locations to the places where the landslides occurred. This possibility is also investigated here.

209 2. Study Area

Our study is applied to the area of Rolante River basin, located in Rio Grande do Sul state, in Brazil. In Fig. 1 the location of the area is indicated. Zooming into it, we observe the rectangular studied area. Rolante River basin is highlighted for reference. It is a watershed with high sloped scarps, located in a predominantly rural area. In this figure, terrain elevation is plotted on background, for reference. The scars of the 2017 landslide events are also plotted.

On January 5th, 2017, a series of landslides occurred in the area (scars 217 marked on Fig. 1). They were triggered by intense rainfall on that day and 218 showers that had been occurring for days. The exact amount of rain in this 219 area remains unknown. It was a convective rainfall, very localized, typical of 220 summer season, therefore hard to be correctly measured by satellites. According 221 to Tropical Rainfall Measuring Mission (TRMM) Multisatellite Precipitation 222 Analysis (TMPA) (Huffman et al., 2007), a spatial average of 142.44 mm of 223 rainfall was recorded in the studied area, during two and a half days (57h). In 224 opposition, a technical report released (Secretaria Estadual do Meio Ambiente 225 and Grupo de Pesquisa em Desastres Naturais, 2017) provided rainfall measurements 226 of seven local farmers in their properties, varying from 90 to 272 mm in 24 h, 227 although caution should be exercised since some of their equipment did not 228

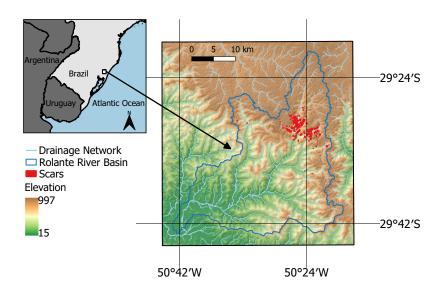


Figure 1: Map of the study area and the location of the landslide scars.

229 follow technical specifications.

Even though no one was physically hurt by the natural hazard, the need for zonation in this area is a pressing issue. Zonation starts with a hazard susceptibility assessment, in this case, a landslide susceptibility assessment.

The original data for this area is from Advanced Land Observing Satellite-1 233 (ALOS), a mission of the Japan Aerospace Exploration Agency (JAXA) that 234 used the Phased Array type L-band Synthetic Aperture Radar (PALSAR) to 235 map the surface of some areas on Earth (ASF DAAC, 2015). The DEM was 236 downloaded through Alaska Satellite Facility (ASF) Distributed Active Archive 237 Center (DAAC), that operates the North American Space Agency (NASA) 238 archive of Synthetic Aperture Radar (SAR) data from a variety of satellites 239 and aircraft, in support of NASA's Earth Science Data and Information System 240 (ESDIS) project. According to Arnone et al. (2016), the DEM with 10 m 241 spatial resolution was better suited for landslide susceptibility mapping using 242

ANNs than the ones with 2, 5, 20, 30, 40, and 50 m resolution. Among the 243 DEMs available for this region, the one with the highest spatial resolution is the 244 one that was chosen by the present authors for this research, which is ALOS 245 PALSAR, with 12.5 m resolution. The DEM and the scar inventory are the only 246 two data sources used for this model, every other attribute is generated based 247 on the DEM by using software QGis. Ten attributes were generated, plus the 248 terrain elevation, which is the DEM itself. The generated attributes are (Fig. 249 2): 250

- Aspect: the orientation, in degrees, of the hill slope;
- Hillshade: a grayscale 3D representation of the surface;
- Natural Logarithm of Flow Accumulation: flow accumulation based on flow direction, in log scale;
- Planar Curvature: the horizontal curvature of terrain;
- Profile Curvature: the vertical curvature of terrain;
- Slope: the declivity of the slope, in degrees;
- Slope Length and Steepness Factor: also known as LS-factor, it is a term
 of Universal Soil Loss Equation (USLE) for soil erosion;
- Topographic Wetness Index (TWI): an index that considers uphill drainage area and slope, ln(Area/tan(SLOPE));
- Valley Depth: the vertical distance to the channel network base level;
- Vertical Distance to Channel Network (VDCN): the vertical distance to the nearest draining channel.
- Fig. 2 shows the spatial distribution of the attributes. The attributes chosen for this application are believed to provide significant data to the model, in

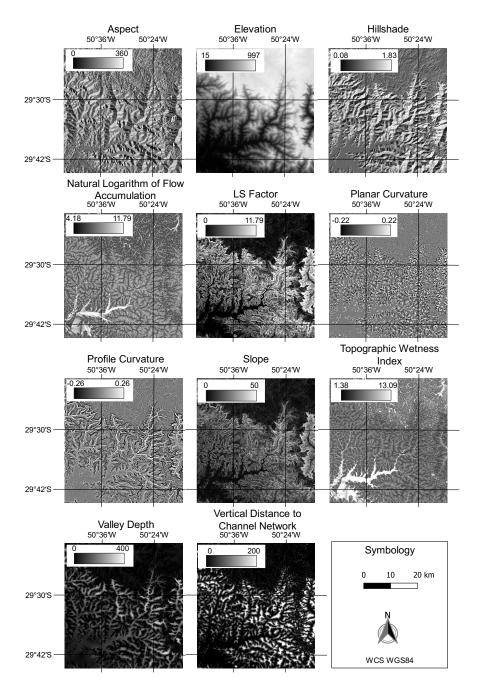


Figure 2: Attributes on the study area.

terms of relationships between pixels, and to provide information about the 267 relative location of each pixel on the basin. Elevation can provide the model 268 with a general sense of location of the pixel, e.g. if the sample is located in 269 the valley or in the plateau. Valley Depth and VDCN provide information 270 of how distant (vertically) is the pixel from the valley, and from the channel 271 network. Curvatures provide general information about the terrain, and Profile 272 Curvature can help the model to determine the stability of an area. TWI and 273 the Natural Logarithm of Flow Accumulation show the areas that are more 274 prone to have bodies of water, Slope and LS Factor show the steepest and more 275 prone to erosion areas, while Aspect and Hillshade provide information about 276 the orientation of the terrain. Statistics for the attributes are presented in Tab. 277 1. The maximum Elevation for the area is 997 m, and two measurements that 278 interpret the vertical depth, Valley Depth and VDCN, have maximums between 279 400 and 500 m. Average slope in the area is 13.1° , but, in the scarps area, it can 280 get as high as 79.04°. Planar and Profile Curvature distributions, as expected, 281 are centered in zero. 282

Attribute	Minimum	Maximum	Average	Std. Dev.
Aspect	0.00	359.73	178.67	102.78
Elevation	15.00	997.00	543.77	312.00
Hillshade	0.00	2.29	0.96	0.44
In of Flow Accumulation	5.05	20.55	7.98	1.90
LS Factor	0.00	122.97	3.98	3.91
Planar Curvature	-1.35	1.18	0.00	0.11
Profile Curvature	-3.17	1.70	0.00	0.13
Slope	0.00	79.04	13.10	9.82
TWI	0.59	25.23	7.24	2.93
Valley Depth	0.00	400.94	55.57	58.20
VDCN	0.00	454.17	36.66	50.66

Table 1: General statistics for each attribute, inside the study area.

Dimensionality reduction was not performed because prior research has shown that these eleven attributes conceive new information to the model, and removing some of them causes the model performance to drop(Lucchese et al., 2020).

²⁸⁶ 3. General Sampling Procedure

Sampling of both occurrence and nonoccurrence samples was done on QGis 3.4. The points to be used as occurrence samples were acquired from inside the mapped scars polygons. To sample the maximum number of points, sampling points were located on a grid, so that each different point of the raster inside the polygons generates a sample. With this procedure, 6740 occurrence samples were generated.

We used a ratio of 50% occurrence and 50% nonoccurrence samples, in order 293 to have a balance between them. Nonoccurrence samples were sampled inside 294 thirteen different groups of polygons so that their location could be analyzed. 295 Their number was held constant and equal to 6740 for all cases. The sampling 296 procedure applied inside the polygons is a random sampling with a minimum 297 distance of 17.7 m. This distance is the hypotenuse of a square of side 12.5 m 298 (the raster resolution) and is set to ensure that each of the points is located over 299 a different raster point. 300

4. Nonoccurrence sampling

One of the most relevant questions about nonoccurrence sampling is how distant from the landslide scar should the sample be in order for the place to be considered safe. The first set of cases comprises this aspect, consisting of six cases in which the minimum distance from the scars in nonoccurrence sample differ. This minimum distance to the scars is here called buffer.

The polygon of the buffer areas was created to have 5 km maximum distance 307 from the scars. The minimum distance from the scars is varied, ranging from 308 0 m to 2.5 km. In the first group of cases, called Buffer Only or simply BO, 309 nonoccurrence samples are acquired solely from this area. The sampling areas 310 for each case are presented on Fig. 3. BO cases represent the logic of sampling 311 from places close to the area where the landslides occurred because they may 312 have had the same triggering conditions yet no landslides occurred. The rainfall 313 (and other weather conditions) may have been more intense in the proximity 314 of the mapped rainfall-induced landslides. Therefore, in the sampling by buffer 315 area, restricting the samples to this radius implies in an assumption that, in this 316 area, the rainfall was homogeneous and other terrain attributes influenced the 317 occurrence (or not) of landslides. Our aim is that the ANN should be capable 318 of identifying the occurrence of landslides from the input variables provided. 319

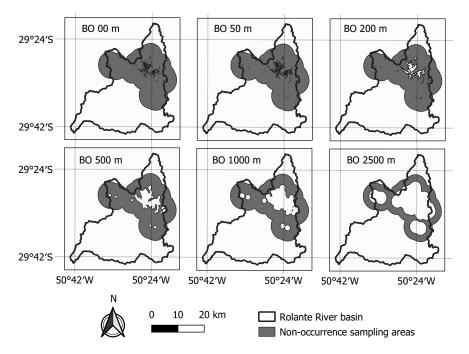


Figure 3: Buffer Only (BO) nonoccurrence sampling areas, for different minimum distances from scar area.

Another possible area for acquiring nonoccurrence samples is a rectangle 320 in the valley area. This rectangle is shown on Fig. 4. The valley area is 321 notably a safe region and its employment represents the nonoccurrence sampling 322 procedure in which areas known not to be prone to landslides are taken as 323 nonoccurrence samples. This rectangle in the lowlands has a physical meaning, 324 because the landslides as they are a gravitational sediment movement, cannot be 325 triggered in flat areas. Therefore, this is a way of integrating a priori knowledge 326 in order to help the ANN model in the classification process. 327

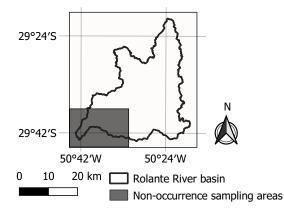


Figure 4: Rectangle Only (RO) sampling area.

The last sample group, named Buffer and Rectangle (BR), was trained 328 considering both the buffers used for BO, and the rectangle used on RO (Fig. 329 5).One should notice, even if two polygons are used, the number of total 330 nonoccurrence samples is held constant, therefore the sampling points are simply 331 more sparse within these areas. BR group is used to analyze the effect of 332 combining areas from BO and RO in the resulting maps and statistics. We also 333 investigate if the maps and metrics would be close to BO or RO, or if they have 334 their own definite characteristics. 335

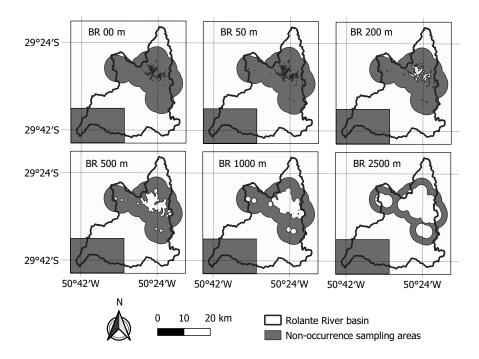


Figure 5: Buffer and Rectangle (BR) nonoccurrence sampling areas, for different minimum distances from scar area.

336 5. Artificial Neural Networks employed

The Artificial Neural Networks (ANNs) used are of the type Multilayer 337 Perceptron (MLP), otherwise referred as Back-propagation Neural Network by 338 some authors. The MLP employed consists of three layers: input, hidden, and 339 output. The use of an ANN with one hidden layer is based on the work of 340 Hornik et al. (1989), which stated that a neural network with a single hidden 341 layer is able to represent any measurable relationship $r\,:\,R^n\,
ightarrow\,R^m$ if it is 342 appropriately trained and relies on a sufficient number of neurons. Therefore, 343 for the present case, building an ANN with more than one hidden layer is not 344 necessary. In the hidden layer used, 30 neurons are employed. The number of 345 neurons in the hidden layer was chosen by using an in-house developed method. 346 The ANN should be able to perform as accurately for the validation sample 347 as a purposefully oversized model that has been trained without overfitting. 348 Therefore, resulting in a parsimonious model, without loss of generalization 349 capacity when compared to models with higher complexity. This method was 350 further described in Lucchese et al. (2020). In the input layer, the 11 attributes 351 are used. The output, consisting of one variable, susceptibility, varies from 0 352 (low susceptibility) to 1 (high susceptibility). 353

Some commonly employed attributes were not used to train our ANNs. 354 Land use was not employed because the region of the mapped landslide scars is 355 uninhabited, and that could lead our model to the erroneous assumption that 356 urban areas are not prone to landslides. Public lithology maps for this region 357 are available only in large scales, not compatible with our area. If used, by the 358 available classification, all scars would be located over the same lithologic unit, 359 and so using a lithology map would not improve training in this case, as well. 360 Instead, only attributes that can be generated from a DEM were used. This 361 possibly makes the model and analysis more generalizable since DEMs are freely 362

³⁶³ available for most of the Earth.

³⁶⁴ For the ANNs, the delta rule used is:

$$\omega_t = \omega_{t-1} + \tau \delta P_k + mo(\omega_{t-1} - \omega_{t-2}) \tag{1}$$

in which ω are the weights, τ is the learning rate, P_k is the input of layer k, and *mo* is the moment, set equal to 0.96 unless the error increased in the last epoch. t denotes the current epoch. δ is defined as $e_k s'_k(\eta_k)$, for which e_k is the error on layer k and $s'_k(\eta_k)$ is the activation function derivative. The activation function employed is unipolar sigmoid.

Learning rate used for training is heuristically varied and based on Vogl et al. (1988) work. The initial rate for all ANNs is $\tau = 0.00001$. If, in a given epoch, the square error rises, $\tau = 0.5\tau$, if it drops, $\tau = 1.1\tau$.

Training uses cross-validation method. For that, the original samples are 373 divided in three: training (50%), validation (25%) and verification (25%). The 374 70/30 ratio between training and testing samples, commonly employed on papers 375 of the landslide susceptibility mapping knowledge area, could not be simply 376 applied to cross-validation training, because, in this case, three sets of samples 377 are needed. The first set is used for training the ANN, while the second one is 378 executed at each epoch during the training, to ensure that the ANN does not 379 overfit to the training data. Practically, training is stopped if no improvement 380 is made in the validation sample in 10,000 epochs, thus the weights from the 381 last epoch when the errors on the validation sample decreased are chosen. 382 Verification (or test) set is used mainly for metric calculation because it did 383 not participate in training phase, therefore it is likely unbiased. The three sets 384 must be satisfactorily representative of the whole, and the training sets used 385 by most authors are larger than the other two. Based on that, we distributed 386 the samples in a ratio of 50/25/25 (training/validation/verification). For each 387

of the sets, the 50-50% ratio between occurrence and nonoccurrence samples is
kept. All statistics here presented are calculated based on verification samples,
that do not interfere in training.

For the sampling division, the training samples are first selected, without 391 replacement. A random distribution is applied to acquire 50% of the occurrence 392 and 50% of the nonoccurrence samples available, making sure the extreme values 393 of each attribute are selected. This is done to provide a training set with as 394 much amplitude of values as possible for the ANN training, to improve ANN 395 generalization capability. These samples compose the training sample, which 396 is 50% of the total samples available (realistically, it can be 50.00% - 50.16%, 397 because of the 22 extreme values). Then, randomly, 25% of total occurrence 398 samples, and 25% of total nonoccurrence are selected, without replacement, from 399 the remaining samples, to compose the validation sample. The 25% of samples 400 remaining (realistically, 24.84% - 25.00%) compose the verification sample. 401

For each case, five different sampling divisions between training, validation 402 and verification are made. This is done to ensure the reliability of our analysis 403 since the distribution of the verification samples can generate sets that have 404 easier or harder to classify verification samples. We believe that, taking the 405 evaluation metrics average from five divisions, the presumable variability is 406 attenuated. The average of the verification set evaluation metrics for these 407 five sampling divisions is calculated and presented as the final evaluation metric. 408 The susceptibility maps presented for the cases are also the average between the 409 maps generated by these five ANNs. Fig. 6 illustrates the five sampling divisions 410 for one case, specifically, RO, showing the locations of training, validation and 411 verification samples, that are visibly randomly distributed along the maps. 412

For the present analysis, 325 ANNs were trained. A summary of them is presented on Tab. 2. Thirteen cases for different nonoccurrence sampling

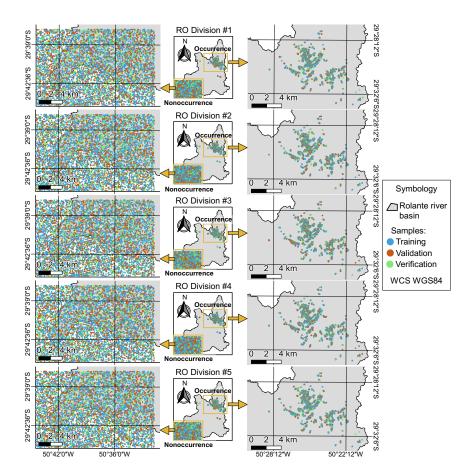


Figure 6: Location of training, validation and verification samples for each sampling division of case RO.

locations are analyzed. But, within the global samples acquired from the 415 polygons, five different sampling divisions between training, validation and 416 verification are made. Each of the ANNs used to calculate the average is the one 417 chosen from five other trained ANNs with same sampling division and different 418 initial weights. Five repetitions with different random initial weights are trained 419 and the ANN with the best AUC on the validation sample is chosen. Because 420 the division between training, validation and verification is constant for the five 421 repetitions, AUC metric can be considered unbiased and the only aspect being 422 measured is the effectiveness of the initial weights. From the five trained ANNs, 423 one is chosen. Its evaluation metrics for verification sample are calculated and 424 its map is generated, in order to serve as one of the five factors to calculate the 425 general case map and metric. A flow chart for this methodology is presented on 426 Fig. 7. 427

Table 2: Summary of ANNs and cases presented				
	Number of cases			
Sampling area	6 sizes of buffers $+$ 6 sizes of buffers with rectangle $+$ 1 only the rectangle = 13 types of areas			
Sampling division	5 random sampling divisions for each			
Initial weights	5 repetitions of training with different initial weights			
Total number of ANNs trained	13*5*5 = 325			

Our in-house ANN code was fully developed on Matlab platform. Earlier versions of this algorithm were employed in the papers of Fantin-Cruz et al. (2011), Dornelles et al. (2013), Oliveira et al. (2015), Moreira de Melo and Pedrollo (2015) and Sari et al. (2017).

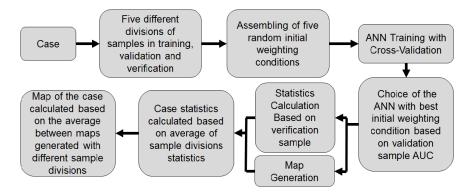


Figure 7: Flow chart of the ANNs presented on the present paper.

432 6. Evaluation metrics and analysis

In this paper, two main evaluation metrics are presented and analyzed,
accuracy and AUC (DeLong et al., 1988).

Accuracy is the rate of right answers provided by the model, or

$$acc = \frac{TP + TN}{TP + TN + FP + FN} \tag{2}$$

in which TP is True Positive (model predicted TRUE, it was a hit), TN is True 435 Negative (model predicted FALSE, it was a hit), FP is False Positive (model 436 predicted TRUE, missed it), and FN is False Negative (model predicted FALSE, 437 missed it). The accuracy measures the ability of the model to predict the right 438 (boolean) answer, based on the samples provided. Our ANN model output is 439 a continuous value between 0 (low susceptibility) and 1 (high susceptibility). 440 To calculate variables TP, TN, FP, and FN, a threshold over which the output 441 is considered susceptible must be established. Instead of choosing an arbitrary 442 threshold, its value is varied from 0 to 1, and accuracies are calculated for each 443 threshold within the limits. The threshold that provides the highest accuracy is 444 chosen, usually gravitating around 0.5. Accuracy is one of the main evaluation 445 metrics used to evaluate models, and, generally, it is considered that, the closer 446

 $_{447}$ to 1, the better.

AUC is the area under the Receiver Operator Characteristic (ROC) curve, which is True Positive Rate (TPR) by False Positive Rate (FPR), for a range of thresholds. TPR is TP/(TP + FN) and FPR is FP/(FP + TN). Generally, models present an AUC between 0.5 and 1, with models closer to 1 usually being considered more reliable.

In this paper, the evaluation metrics *acc* and AUC presented in the following section always refer to the ones calculated based on the verification sample. The same model, applied to different samples, generates different *acc* and AUC values.

457 7. Results

In this section, results for the 13 cases are presented. Evaluation metrics
AUC and *acc*, calculated based on verification samples, are shown. The resulting
landslide susceptibility map for each case is also presented.

In Tab. 3, the average of the verification sample AUC and accuracy acc for 461 different sampling divisions is presented for each case. AUC varies from 0.94 462 to 1, while accuracies range from 89% to 100%. Evaluation metrics based on 463 the Buffer Only (BO) sampling are lower than those from Buffer and Rectangle 464 (BR). Rectangle Only (RO) presented the best evaluation metrics of all, for 465 which AUC is 1 and accuracy is 100%, indicating all the models trained achieved 466 100% of right classifications. These evaluation metrics were calculated based on 467 the verification samples presented on Fig. 6, and averaged for all five divisions. 468 For the RO case, in all divisions, FN and FP are zero, and TP and TN are at 469 their maximum values, for a given threshold. It also means that as TPR may be 470 written as TP/(TP+0), if $TP \neq 0$, this results in TPR = 1. Analogously, FPR 471 is 0/(0+TN) = 0, therefore, for $TN \neq 0$, FPR = 0. This occurred because all 472

the occurrence samples were in the scarped areas and all the nonoccurrence
samples are in the rectangle on the valley (in the training, validation and
verification sets), resulting on the fact that the model reproduced this pattern.
Minimum distances to scars influences the resulting evaluation metrics values.
Between cases of the same group, the larger this distance, the higher the AUC
and the acc.

		AUC	acc
Buffer Only (BO)	BO 00m	0.9409	89.45%
	BO 50m	0.9494	90.26%
	BO 200m	0.9524	90.67%
	BO 500m	0.9569	91.18%
	BO 1000m	0.9586	91.24%
	$\mathrm{BO}~2500\mathrm{m}$	0.9662	92.28%
Buffer and Rectangle (BR)	BR 00m	0.9616	92.33%
	BR 50m	0.9647	92.28%
	BR 200m	0.9682	93.05%
	$\rm BR~500m$	0.9686	92.96%
	$\rm BR~1000m$	0.9680	93.19%
	$\rm BR~2500m$	0.9806	95.09%
Rectangle Only (RO)		1.0000	100.00%

Table 3: Summary of cases and their verification sample AUC and acc.

Part of our analysis consists of the observation of the susceptibility maps generated. Thus, it is necessary to plot maps for each case. These maps are simple averages of the maps generated from the five different sample divisions (in training, validation and verification, see Tab. 2). In this paper, for the maps shown, the range of susceptibility is continuous, as the output is provided by the ANN. No classification or alteration was performed prior to map plotting.

In Fig. 8, resulting susceptibility maps are shown for the six cases comprised on the Buffer Only non-ocurrence sampling. All the six maps generated using this nonoccurrence sampling procedure are satisfactory and tend to present scarped areas as susceptible. BR 200m, BR 500m and BR 2500m show non-null ⁴⁸⁹ susceptibility values in places in the top of the mountain, generally considered⁴⁹⁰ safe.

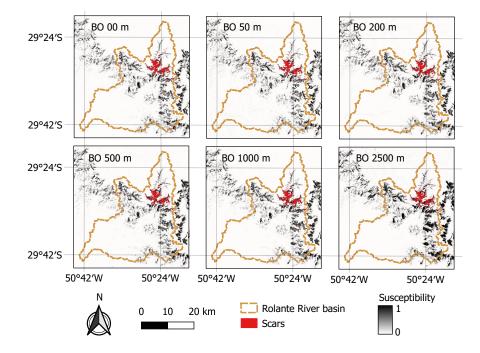


Figure 8: Buffer Only (BO) resulting susceptibility maps.

Hazard susceptibility maps were also plotted for Buffer and Rectangle cases
(Fig. 9). They are very alike the maps generated for cases of group BO. Some
of these maps also present diversions on the mountain top area.

A susceptibility map was generated based on the models of case Rectangle 494 Only, that considers only an area in the valley as non-susceptible (Fig. 10). 495 According to this map, the plateau area would be considered susceptible, which 496 is known to be a misclassification. Comparing Fig. 10 to Fig. 6, it is possible to 497 see that the nonoccurrence samples (for training, validation and verification) are 498 contained in the area classified as not susceptible, and the occurrence samples 499 (for training, validation and verification) are contained in the area classified 500 as susceptible. Therefore, they were all correctly classified, corroborating the 501

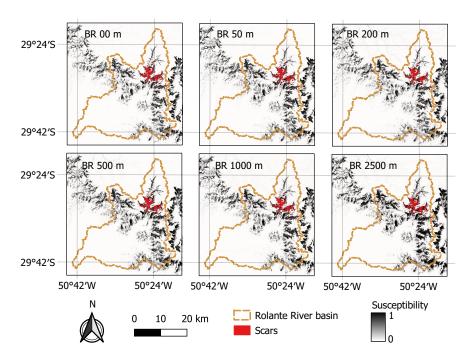


Figure 9: Buffer and Rectangle (BR) resulting susceptibility maps.

⁵⁰² evaluation metrics AUC=1 and acc=100% presented in Tab. 3. It is the least
⁵⁰³ constrained case, as well, and would not be considered suited for zonation
⁵⁰⁴ because a vast area is considered susceptible.

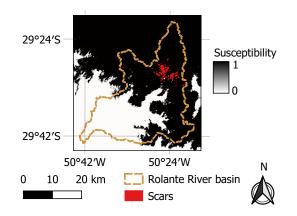


Figure 10: Rectangle Only (RO) resulting susceptibility map.

505 8. Discussions

If the criterion to select not susceptible areas was similar to the one used by 506 Gomez and Kavzoglu (2005); Choi et al. (2010), the selection of nonoccurrence 507 samples would be based on selecting places known not to be prone to landslides. 508 such as the valley area. For this reason, this sampling would be somewhat 509 similar to using a rectangle in the valley area, such as done on case Rectangle 510 Only (RO). As observed, this sampling provided the best evaluation metrics, 511 since every sample was correctly classified. If we were to choose between 512 nonoccurrence sampling methods based only on the evaluation metrics analyzed, 513 we would point RO case as the best option. However, it should be noted that the 514 evaluation metrics are not suited for direct comparisons in this case, because the 515 verification samples composition is different. Also, when the map is observed, 516 and, specially, when it is confronted with maps generated with samples based 517 on other procedures, the difference is clear. The map generated by RO is not 518 constrained, it classifies a vast area as susceptible, including the plateau area 519 which is known for not being susceptible to landslides. That may be considered, 520 depending on the point of view, as incompatible with reality. It would as well not 521 be suited for hazard zonation for this motive. The reason it has high evaluation 522 metrics has no connection with being more precise - in fact, it is the opposite 523 the samples provided as a dataset for training are too easy to classify. They 524 are so distant from each other, and so different in many aspects that even a 525 'loose', 'careless' classification would classify every single one of them correctly. 526 In other words, it is not hard for the model to achieve 100% accuracy because 527 the samples themselves are biased. This may also be the reason why, in Gomez 528 and Kavzoglu (2005), high accuracy was achieved, even if the map shown seems 529 to reflect an interpretation of the terrain Elevation attribute. 530

Zhu et al. (2019) also observed this effect. Models based on nonoccurrence 531 samples that are very different from the occurrence samples provide higher 532 accuracies, although the maps generated based on them roughly overestimate 533 occurrence areas. This resonates to what is observed by the present authors. 534 Hong et al. (2019) results showed that sampling methods that acquire nonoccurrence 535 samples in a similar setting but farther from occurrence samples result in maps 536 with larger susceptible areas, also in agreement with the present analysis. This 537 is not necessarily wrong or provides worse maps, although excessive intervention 538 of human expert knowledge-based processes on dataset forming hinders the 539 possibilities for the ANNs to find their own ways. 540

The evaluation metrics were calculated to test the intrinsic adjust of each 541 model, in which the RO case resulted in a perfect adjust to the samples that 542 were provided to it. However, notably, the evaluation metrics hereby cited are 543 not calculated based on the same verification sample, as they would be in an 544 ideal setting. That said, the same effect discussed for RO can be observed with 545 the increase on the minimum distance (internal buffer) on which the sample is 546 acquired. Even if all BO cases are generating similar maps, the farther from 547 the scars these samples are, the easier they are to classify. On BR samples, the 548 evaluation metrics of the models were in between the values of BO and RO, 549 but the maps looked much more like BO maps. It is possible to think that the 550 easily classifiable samples, provided by the rectangle on the lowlands, made it 551 easier for the model to classify the verification set, which is acquired from the 552 same sample pool as the training and validation sets for each case, and this 553 pool had now easy-to-classify samples. We should remark that easier-to-classify 554 does not equate directly to being better because it does not force the model to 555 train more in order to discriminate between samples that are alike, but produce 556 different outcomes, and purposeful comparisons can only be done if the metrics 557

⁵⁵⁸ are calculated based on similar samples.

As observed by Zhu et al. (2018), the existence itself of the nonoccurrence 559 samples in the calibration/training of a method has a remarkable effect on 560 its resulting maps. They also discussed that methods that use nonoccurrence 561 samples tend to constrain the over-prediction of high susceptibility. With the 562 analyses here presented, we show that not only their presence is important, but 563 their location and their acquisiton process are as well relevant. Many previous 564 works had not presented the location neither commented on the method used 565 to extract nonoccurrence samples, and yet, as we observe, this information is 566 relevant to interpret the resulting evaluation metrics correctly. 567

568 9. Conclusion

In the present paper, we have provided answers to pressing questions regarding nonoccurrence samples used to train ANN models for landslide susceptibility assessment. Using 13 cases with different locations for the nonoccurrence samples, 325 ANNs were trained to provide a reliable outlook on this subject.

For the conducted analyses, AUC and accuracy were chosen as example 573 evaluation metrics because they are two of the most commonly used. Although 574 more research in this area is needed for all possible methods for nonoccurrence 575 sampling to be contemplated, we showed that the locations of these samples 576 are very relevant, with visible effects on the generated map. By intervening 577 and choosing nonoccurrence samples that are distant and have very different 578 attributes from the occurrence ones, we have shown that, using this configuration, 579 ANN, as it is a data-driven model, is not capable of acquiring the necessary 580 knowledge in order to correctly discriminate between susceptible and non-susceptible 581 areas. This is possible to observe in the maps generated, which are not constrained. 582 A probable explanation to why occurrence and nonoccurrence samples used to 583

train the models tend to be different in these settings is that the classification 584 human knowledge allows us to do (such as choosing the lowlands as the nonoccurrence 585 area) is likely not thorough enough. This is one of the reasons why researchers 586 usually do not rely solely on human perception for susceptibility mapping, using 587 models instead. Even if, in this case, AUC and acc metrics are maximized, 588 because all classifications are right, this happens because the sample has a biased 589 configuration that makes it too easy for the model to provide the right output. 590 Expert knowledge is very important to landslide-related studies. However, in 591 many cases, this expert knowledge intervention should, instead of being applied 592 on the formulation of the sample, (e.g. including a rectangle on the lowlands), 593 be applied to the delimitation of the application areas of the final ANN model. 594 Therefore, a possible course of action would be admitting a priori that the flat 595 regions are not susceptible and, based on that, not generating the maps with 596 the model in these regions, if a problem in which the model has not captured 597 the knowledge of how to classify the lowlands is observed. Another way to put 598 it, one can say that what is meant with the inclusion of easily classifiable areas 599 is achievable anyway by defining the application areas possible to be mapped 600 by the model. 601

In many previously published papers, the locations and methods of acquisition of nonoccurrence samples are not presented or commented. However, we have shown that these are important aspects to be considered when analyzing the evaluation metrics of an ANN model for landslide susceptibility. Overall, based on the empirical evidences presented, we can state that using easily classifiable samples, the model may present high accuracy and AUC, without necessarily this equating to the generation of generalizable map.

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